

Radio occultation experiment of the Venus atmosphere and ionosphere with the Venus orbiter Akatsuki

Takeshi Imamura¹, Tomoaki Toda¹, Atsushi Tomiki¹, Daichi Hirahara¹, Tomoko Hayashiyama¹, Nanako Mochizuki¹, Zen-ichi Yamamoto¹, Takumi Abe¹, Takahiro Iwata¹, Hirotomo Noda², Yoshifumi Futaana³, Hiroki Ando⁴, Bernd Häusler⁵, Martin Pätzold⁶, and Alexander Nabatov⁷

¹*Institute of Space and Astronautical Science, Japan Aerospace Exploration Agency, 3-1-1, Yoshinodai, Sagami-hara 252-5210, Japan*

²*National Astronomical Observatory of Japan, 2-21-1 Osawa, Mitaka, Tokyo 181-8588, Japan*

³*Swedish Institute of Space Physics, Box 812, SE-981 28, Kiruna, Sweden*

⁴*The University of Tokyo, 7-3-1 Hongo, Bunkyo-ku, Tokyo 113-0033, Japan*

⁵*Institut für Raumfahrttechnik, Universität der Bundeswehr München, D-85577 Neubiberg, Germany*

⁶*Institut für Geophysik und Meteorologie, Universität zu Köln, D-50923, Köln, Germany*

⁷*Ukrainian Academy of Science, 4, Chervonoprapornaya Str., Kharkov, 61002, Ukraine*

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The Radio Science experiment (RS) in the Akatsuki mission of JAXA aims to determine the vertical structure of the Venus atmosphere, thereby complementing the imaging observations by onboard instruments. The physical quantities to be retrieved are the vertical distributions of the atmospheric temperature, the electron density, the H₂SO₄ vapor density, and small-scale density fluctuations. The uniqueness of Akatsuki RS as compared to the previous radio occultation experiments at Venus is that low latitudes can be probed many times thanks to the near-equatorial orbit. Systematic sampling in the equatorial region provides an opportunity to observe the propagation of planetary-scale waves that might contribute to the maintenance of the super-rotation via eddy momentum transport. Covering the subsolar region is essential to the understanding of cloud dynamics. Frequent sampling in the subsolar electron density also helps the understanding of ionosphere dynamics. Another unique feature of Akatsuki RS is quasi-simultaneous observations with multi-band cameras dedicated to meteorological study; the locations probed by RS are observed by the cameras a short time before or after the occultations. An ultra-stable oscillator provides a stable reference frequency which is needed to generate the X-band downlink signal used for RS.

Key words: Venus, radio science, radio occultation, exploration.

1. Introduction

Radio occultation is one of the major applications of radio science in space missions, and has played a central role in determining the vertical structures of planetary atmospheres from the early stage of the planetary exploration in the 1960's (e.g., Eshleman *et al.*, 1987; Tyler, 1987). In a radio occultation experiment conducted with an orbiter, the spacecraft transmits radio waves toward a tracking station on the earth and sequentially goes behind the planet's ionosphere, neutral atmosphere, and solid planet as seen from the tracking station, and reemerges in the reverse sequence. During such occultation events the neutral and ionized atmospheres of the planet cause bending, attenuation and scintillation of the radio waves, from which information on the atmosphere along the ray path is obtained. Under the assumption of local spherical symmetry, the measurements yield vertical profiles of refractive index and absorption coefficient. The refractive index profiles yield temperature profiles by assuming hydrostatic balance. Among the

merits of this technique are its high vertical resolution and temperature resolution, which are discussed in Sections 4.4 and 5.4.

The Radio Science experiment (RS) in the Akatsuki or Venus Climate Orbiter mission (PLANET-C project) of Japan Aerospace Exploration Agency (JAXA) will apply this technique to study the atmosphere of Venus (Nakamura *et al.*, 2007, 2011). Although radio occultation experiments have been conducted many times in the previous Venus missions, dense sampling at low latitudes and coordination with other measurements will enable a unique, efficient observation of the atmospheric structure and its temporal variation. Radio science experiments rely on the extreme frequency stability of both the onboard radio wave source and the recording system at the ground station. Akatsuki RS employs an ultra-stable oscillator (USO) as an onboard reference frequency source.

Akatsuki, the first Venus probe of Japan, was launched on May 20 (UT), 2010, and the Venus orbit insertion maneuver for Akatsuki on December 7, 2010 has failed. At present the spacecraft is orbiting the Sun, and it will have a chance to encounter Venus 5–6 years later. JAXA is examining the possibility of conducting an orbit insertion maneuver again at this opportunity. This paper describes the onboard and

ground-based systems, as well as the measurement principle, numerical analysis technique, and observation strategy in the original plan. These will be largely unchanged in the renewed plan.

2. Scientific Background

Previous radio occultation observations of the Venusian atmosphere, including those conducted by Mariner 5, Mariner 10, Pioneer Venus Orbiter (PVO) and Venus Express have provided a variety of information on the atmospheric structure. Temperature soundings by radio occultation showed that both the latitude dependence and local-time dependence are small below the cloud layer which is located around 45–70 km altitude (Kliore and Patel, 1980, 1982). Within the cloud layer (60–70 km) the temperature drops by ~ 20 K around 60–75° latitude, suggesting via thermal wind balance a prominent easterly vertical shear associated with the mid-latitude jet around 60° latitude (Newman *et al.*, 1984; Tellmann *et al.*, 2009). This mid-latitude temperature minimum surrounds the warm pole, creating the so-called polar collar (Taylor *et al.*, 1980). The occurrence of the mid-latitude jets is consistent with the results of cloud tracking (e.g., Rossow *et al.*, 1990). Above the cloud the temperature increases monotonically with latitude, leading to the weakening of the mid-latitude jets with height (Newman *et al.*, 1984). The static stability is near neutral in the middle and lower cloud region (50–55 km), implying vertical convection driven by upwelling thermal radiation, while it is weakly stable below this height and strongly stable above (Fjeldbo *et al.*, 1971; Howard *et al.*, 1974; Tellmann *et al.*, 2009). The overall stable stratification sustains vertical propagation of gravity waves; wavy temperature structures which might be associated with gravity waves have been observed by radio occultation (Howard *et al.*, 1974; Hinson and Jenkins, 1995).

The mixing ratio of H_2SO_4 vapor around 35–50 km altitude can be measured by radio occultation by utilizing the fact that attenuation of radio waves occurs in the Venus atmosphere primarily due to H_2SO_4 vapor in this altitude region, with smaller contributions from CO_2 and SO_2 (Jenkins and Steffes, 1991; Jenkins *et al.*, 1994). H_2SO_4 vapor is a key species in the global-scale sulfur cycle and the physics and chemistry of H_2SO_4 - H_2O clouds (Imamura and Hashimoto, 1998, 2001). The H_2SO_4 vapor density reaches the maximum value of 18–24 ppm around 38–45 km altitude. Above this altitude the density is limited by the saturation pressure, while below this altitude it drops precipitously probably due to thermal decomposition.

Scintillations of radio waves are caused by the movement of the ray path across small-scale density structures in the atmosphere. Woo *et al.* (1980) analyzed the time series of the received signal power and compared their spectra with theoretical scintillation spectra based on the wave propagation theory. They found that a turbulent layer exists around 60 km altitude, and the scintillation power is higher at higher latitudes. An eddy diffusion coefficient of $4 \text{ m}^2 \text{ s}^{-1}$ was estimated for 60 km altitude from the same data set. Leroy and Ingersoll (1996) attributed the scintillations to vertically-propagating gravity waves created by cloud-level convection.

The height range of the Venus' neutral atmosphere accessible by radio occultation is approximately 32–90 km. Below 40 km the defocusing loss and the attenuation by the atmosphere limits the quality of the observation, and 32 km is the lowest accessible altitude, below which the radius of curvature of the ray path becomes smaller than the distance to the planet center (Fjeldbo *et al.*, 1971; Häusler *et al.*, 2006). The atmosphere above 100 km is too thin to be detected. The broad height coverage of radio occultation is a great advantage in the investigation of the vertical coupling among different atmospheric layers; no other technique can cover this altitude range at the same time.

At altitudes above ~ 100 km the electrons in the ionosphere are the major contributors to the ray bending. The peak electron density occurs at around 150 km altitude, and is on the order of 10^5 cm^{-3} on the dayside and 10^4 cm^{-3} on the nightside (Kliore, 1992; Pätzold *et al.*, 2007a). The Venusian nightside ionosphere is thought to be generated by the transportation of electrons from the dayside and the high energy electron impact on the nightside. The ionosphere of Venus is not protected by the planet's intrinsic magnetic field from the impinging solar wind, and thus the thermal and magnetic pressure of the ionosphere will balance the dynamic pressure of the solar wind at the upper boundary of the ionosphere called the ionopause. Previous observations revealed that the ionopause is located at 200–400 km, except for the high solar zenith angle (SZA) ionosphere with $\text{SZA} > 50^\circ$ during the solar maximum, when the ionopause is located at 200–1000 km and the height is highly variable. Frequent measurements at low SZA will complement the previous observations, which were conducted mostly at $\text{SZA} > 30^\circ$ (Kliore and Luhmann, 1991). The structure of the ionosphere is affected by the input of energy and momentum from the solar wind to the upper atmosphere, and thus important for understanding the escape of the atmosphere to space, which should have driven the climate evolution of Venus in a geological time scale.

3. Objectives

The primary goal of Akatsuki RS is to characterize the meteorological processes that might drive the planet-wide easterly wind (super-rotation) as well as to understand the cloud dynamics. For this purpose the temporal and spatial variability of the Venus atmosphere will be studied by retrieving the vertical profiles of the temperature, the H_2SO_4 vapor density, and the intensity of small-scale density fluctuations.

The advantage over the previous missions is the near-equatorial orbit of the spacecraft and a suite of multiband cameras dedicated to meteorological study (Nakamura *et al.*, 2007, 2011). The planned orbit around Venus is a 30 hour-period elliptical orbit near the ecliptic plane with the periapsis latitude of $\sim 10.5^\circ\text{S}$ and the apoapsis latitude of $\sim 10.5^\circ\text{N}$. The direction of orbital motion is westward, which coincides with the direction of the atmospheric super-rotation. The apoapsis altitude is chosen to be 78500 km, or 13 Venus radii (R_V), so that the angular velocity of the spacecraft is roughly synchronized with the 60-m s^{-1} super-rotational flow near the cloud base (50 km) for ~ 20 hours centered at the apoapsis. The periapsis alti-

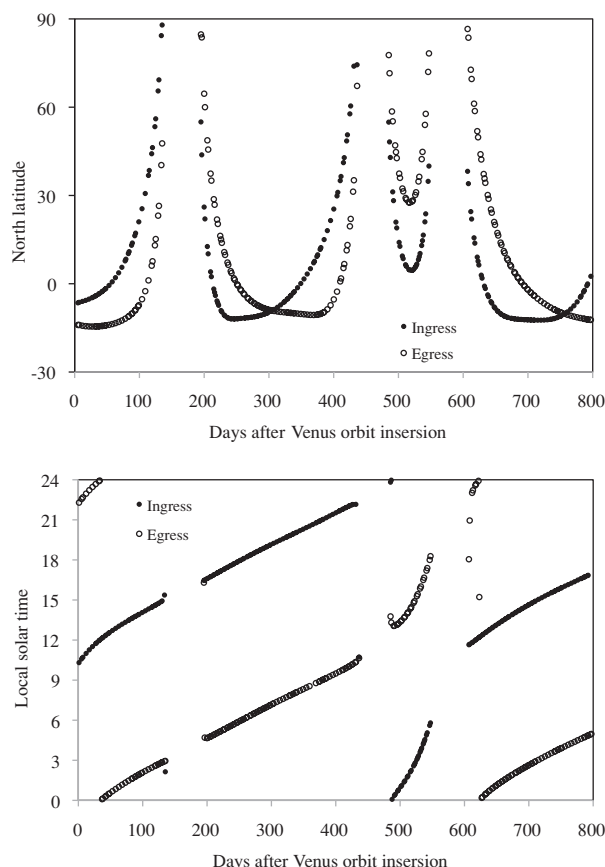


Fig. 1. (upper) Latitudes and (lower) local solar times of the observation points during the nominal mission period in the original plan. Filled circles and open circles indicate ingress and egress occultations, respectively. The observation point is defined as the tangential point of the straight line between the spacecraft and the ground antenna at the moment when the spacecraft is occulted by the solid surface of Venus.

tude is ~ 600 km.

Figure 1 shows the latitude and local time of the observation in the original plan as a function of the Earth days after Venus orbit insertion (VOI), which was scheduled for early December 2010, during the nominal mission period of ~ 2 Earth years. Approximately 200 experiments, each of which includes an ingress and an egress occultations, are planned to be conducted during this 2 years. The uniqueness of the Akatsuki RS is that probed points cluster around the equatorial region. Since the onboard cameras are designed to observe wide areas centered at the equatorial region, the locations probed by RS can be observed by the cameras a short time (minutes to hours) before or after the occultations. The vertical profiles taken by RS and the horizontally-resolved information at several height levels by the cameras complement each other in developing three-dimensional models of the atmosphere.

Systematic long-term sampling on a specific latitudinal band (equatorial region) also provides a unique opportunity to study the propagation of planetary-scale waves such as Kelvin waves and thermal tides, which might play essential roles in sustaining the super-rotation (e.g., Rossow *et al.*, 1990; Yamamoto and Tanaka, 1997; Takagi and Matsuda, 2007). Typically an occultation (an ingress-egress

pair) is observed every 3–4 days from the tracking station. Given this sampling interval, planetary-scale waves with 4–6 days period, which have been detected at the cloud top (e.g., Rossow *et al.*, 1990) would be observed apparently as much longer period (up to several tens of days) waves due to aliasing. However, such long periods correspond to very fast intrinsic phase speeds because the waves observed from the inertial frame are Doppler-shifted by the 4 day-period super-rotation. Such a solution will be rejected based on meteorological considerations, and more realistic waves with periods of several days will be obtained by fitting a sinusoidal function to the data.

The almost complete local-time coverage in the low latitude (Fig. 1) enables the studies of equatorial cloud dynamics which is poorly understood. For example, cell-like structures have been observed near the subsolar region in ultraviolet (Rossow *et al.*, 1980; Markiewicz *et al.*, 2007). The origin of these structures has been unclear, because their horizontal scales of up to several hundreds kilometers seem to be too large for convective cells and the cloud top region is considered to be basically stably stratified (Baker and Schubert, 1992; Toigo *et al.*, 1994). The diurnal variation of the temperature profile to be revealed by RS, especially the possible variation in the depth of the neutral-stability layer, should become a key to understanding the cloud dynamics in this region.

Excursions of the probed points to the northern high latitude occur several times and enable observations of the latitudinal structure. Since the Venus atmosphere is considered to be in cyclostrophic balance, the meridional distribution of the zonal wind can be derived from the temperature distribution by integrating the thermal wind equation with an appropriate lower boundary condition (Newman *et al.*, 1984). This zonal wind distribution will become the basis for understanding the momentum balance of the atmospheric general circulation. The combination of data from Akatsuki RS with those from ESA's Venus Express radio science VeRa (Häusler *et al.*, 2006; Pätzold *et al.*, 2007a; Tellmann *et al.*, 2009), which conducts dense sampling in the high latitude by virtue of the polar orbit, would also enable studies of meteorological processes over broad latitude regions even when the two spacecraft do not orbit at the same time.

Another goal of Akatsuki RS is to study the spatial and temporal variabilities of the ionosphere in response to the variations in the solar wind and the neutral atmosphere. Although Akatsuki is not equipped with a magnetometer and particle instruments, Venus Express has those instruments and would provide supplementary information (Zhang *et al.*, 2006; Barabash *et al.*, 2007) if Venus Express mission is extended till Akatsuki's next Venus orbit insertion. Such a configuration is very optimal for studying the response of the ionosphere to the solar wind condition, because the upstream solar wind conditions and their sudden changes such as interplanetary shock passages and coronal mass ejections can be monitored simultaneously. Sudden changes in the solar wind modify the global characteristics of the Venusian ionosphere, which may increase the ion escape flux from the upper atmosphere (Futaana *et al.*, 2008; Edberg *et al.*, 2010). Energetic electrons at energies ≈ 30 eV (Kliore *et*

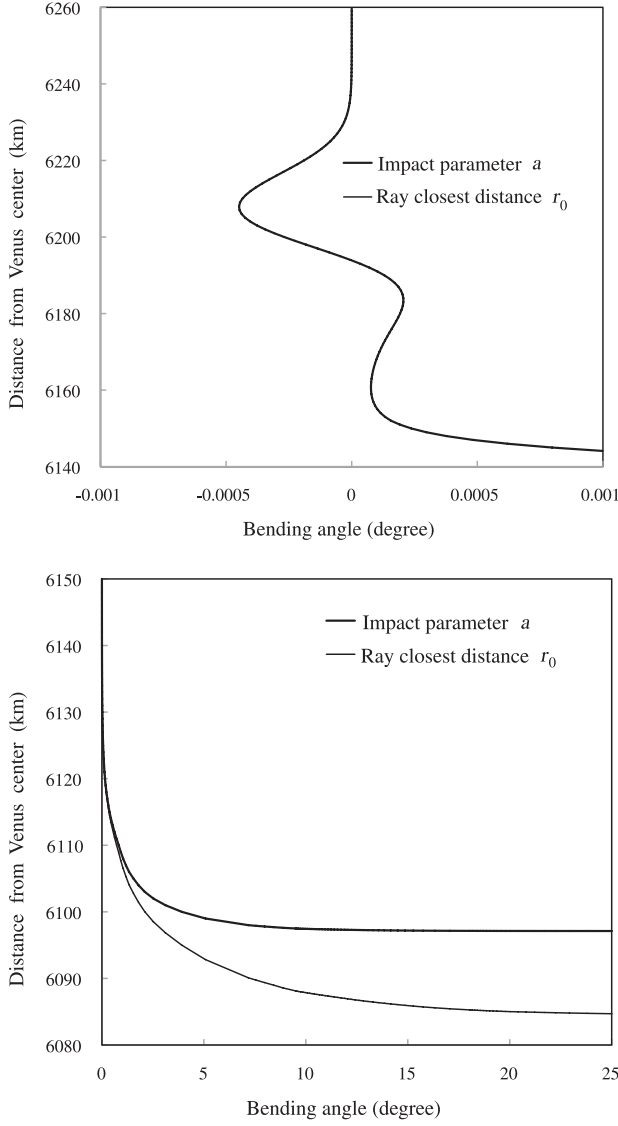


Fig. 3. Relationship between the bending angle α and the impact parameter a (thick curve) and that between the bending angle and the ray closest distance r_0 (thin curve) for a model ionosphere described in the text and the “VIRA” neutral atmosphere model. The radius of Venus is taken to be 6052 km. (upper) Plot in the ionospheric altitude range, where the thick and thin curves almost overlap. (lower) Plot in the neutral atmosphere range.

4.2 Derivation of atmospheric density and temperature

The refractivity μ is related to the refractive index n by

$$\mu = (n - 1) \times 10^6. \quad (4)$$

The μ is the sum of the contributions from the neutral atmosphere and the ionosphere:

$$\mu = VN - \frac{\beta N_e}{f^2} \times 10^6, \quad (5)$$

where V is the refractive volume, N is the number density of the neutral atmosphere, $\beta = e^2/8\pi^2\epsilon m_e \sim 40.3 \text{ m}^3 \text{ s}^{-2}$ with e , ϵ and m_e being the elementary charge, dielectric constant in vacuum and electron mass, respectively, c is the speed of light, N_e is the number density of electrons, and f is the frequency of the carrier signal. On the

assumption that the neutral atmosphere is well mixed, we adopt a constant V of $1.81 \times 10^{-17} \text{ m}^3$ based on the composition of 96.5% CO_2 and 3.5% N_2 using the constants given in Fjeldbo and Eshleman (1968). The neutral and ionospheric contributions are separated in altitude with the boundary around 100 km altitude (see results of Pätzold *et al.*, 2007a). This enables us to retrieve the vertical profiles of the neutral atmospheric density N and the electron density N_e separately.

The vertical profile of the neutral atmospheric pressure, $p(r)$, is derived from the density profile $N(r)$ by integrating the equation of hydrostatic equilibrium:

$$p(r) = p(r_{\text{top}}) + m \int_r^{r_{\text{top}}} N(r')g(r')dr', \quad (6)$$

where m is the mean molecular mass, g is the acceleration due to gravity, and r_{top} is the adopted upper boundary. The ideal gas law relates $p(r_{\text{top}})$ to the atmospheric temperature T at this height as

$$p(r_{\text{top}}) = N(r_{\text{top}})kT(r_{\text{top}}), \quad (7)$$

where k is the Boltzmann’s constant. The boundary condition required for the integration is the value $T(r_{\text{top}})$. The temperature profile $T(r)$ is calculated from $N(r)$ and $p(r)$ using the ideal gas law. The influence of the adopted $T(r_{\text{top}})$ on the calculated $T(r)$ is almost negligible except at the uppermost 10 km (Pätzold *et al.*, 2007a; Tellmann *et al.*, 2009).

4.3 Atmospheric defocusing and absorption

The received signal power varies during each occultation experiment due to atmospheric defocusing and absorption. The former must be taken into account when retrieving the vertical distribution of absorbing materials from the observed signal power.

Atmospheric defocusing is caused by the radial gradient of the refractive index. The defocusing loss is estimated by (Eshleman, 1973)

$$L = \left(\cos \alpha - D \frac{d\alpha}{da} \right)^{-1}, \quad (8)$$

where D is the distance from the spacecraft to the crossing of the ray asymptotes. Figure 4 shows the expected defocusing loss in units of dB, $-10 \log L$, as a function of the ray closest distance r_0 for $D = 1, 2$, and $5 R_V$. The loss increases with D , and it is as large as ~ 26 dB at 40 km altitude (6092 km from the planet center) for a typical D of $2 R_V$.

Once the defocusing loss is estimated as a function of time from trajectory information and the relationship between α and a from the Doppler measurements, one may calculate the total atmospheric absorption from the time series of the received signal power. This time series is converted to a height profile of the absorptivity with the aid of ray tracing on the assumption of a spherically symmetric atmosphere (Jenkins and Steffes, 1991; Jenkins *et al.*, 1994). The absorption due to CO_2 , N_2 and SO_2 is removed from the absorptivity profile based on its dependence on the ambient pressure and temperature. The remaining absorption will be principally due to H_2SO_4 vapor.

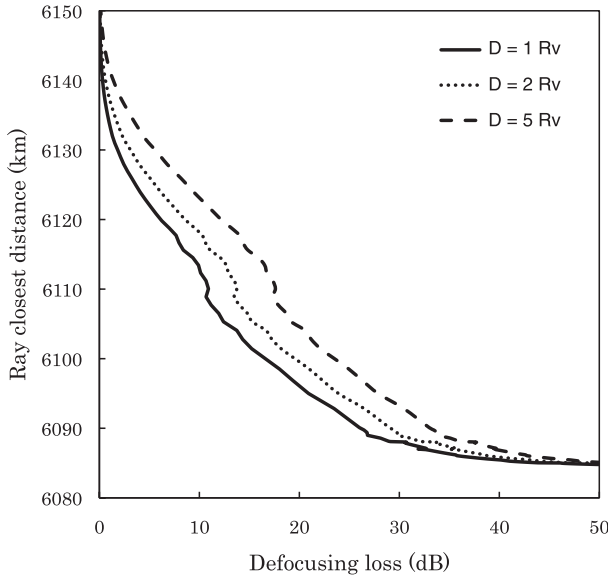


Fig. 4. Defocusing loss as a function of the ray closest distance r_0 for three distances from the spacecraft to the crossing of the ray asymptotes, D .

4.4 Vertical and horizontal resolution

The vertical resolution is limited by the diameter of the first Fresnel zone. The refraction in the atmosphere changes the Fresnel zone shape from circular to elliptical form, and the resulting vertical diameter is (Fjeldbo and Eshleman, 1969; Karayel and Hinson, 1997)

$$d_v = 2\sqrt{\lambda DL}, \quad (9)$$

where $\lambda \sim 3.6$ cm is the wavelength of the carrier signal. Here D is assumed to be much smaller than the distance from the planet center to the receiver. For a typical D of $2 R_V$ and without defocusing loss ($L = 1$), we obtain $d_v \sim 1.3$ km. When defocusing loss is ~ 26 dB at 40 km altitudes, we obtain $d_v \sim 60$ m for the same D .

Letting the typical scale height of $H = 6$ km (corresponding to 60 km altitude) and the planetary radius of $R = 6052$ km, and ignoring the bending of the ray path, the length of the ray path traversing the atmospheric layer with a thickness H is $2((R+H)^2 - R^2)^{1/2} \sim 500$ km. This length is considered the horizontal resolution of the measurement because the atmospheric variations are smeared out approximately within this interval. The orientation of the radio path is near perpendicular to the meridian in most of the cases and the smearing of atmospheric variations occurs along this direction.

5. Observation System

5.1 Radio communication system

Figure 5 shows a block diagram of the Akatsuki onboard radio communication system. The downlink frequency is 8.410926 GHz (X-band) only. During the experiments, one of the X-band transponders (XTRP) is locked to an ultra-stable oscillator (USO), and the transponder signal is amplified by the 23.4 W traveling wave tube amplifier (TWTA). The 8.7 W solid state power amplifiers (SSPA) will not be used in the experiments unless we have trouble

with the TWTA. The gain of the 0.9 m-diameter flat-type slot array antenna (XHGA-T) is 35 dBi, corresponding to a 3 dB full beam width of $\sim 2^\circ$. Since the ray bending far exceeds the beam width (Fig. 2), the spacecraft will perform attitude maneuvers to compensate for the changing direction of the signal path. The equivalent isotropically radiated power (EIRP) is 42.5 dBW when the TWTA is used.

The radio waves transmitted by the spacecraft will be received at the Usuda Deep Space Center (UDSC), which is located at $138^\circ 21' 54''$ East longitude, $36^\circ 07' 44''$ North latitude in Japan. The 64-m dish provides a gain of 72.5 dBi including the feeder loss in X-band, at a system noise temperature of 96 K for a 5 mm hour^{-1} rain and an elevation angle of 15° . The recording system to be used is the 'IPVLBI recorder' which was developed for radio astronomy. The received signals are down-converted to several hundred kHz by an open-loop heterodyne system stabilized by a hydrogen maser (Allan deviation $< 3 \times 10^{-13}$ for 1 s, $< 3 \times 10^{-15}$ for 1000 s) and 8-bits digitized. The sampling rate will be 1 MHz or more so that the carrier signal, whose frequency changes by ~ 100 kHz or more during each occultation experiment, can be confined in the recording bandwidth.

5.2 Ultra-stable oscillator (USO)

The USO (Fig. 6) provides a stable reference frequency (38.22567759 MHz) for the transponder. It was manufactured by TimeTech GmbH in Germany and is a heritage from the USOs flown onboard the ESA's Rosetta (Pätzold *et al.*, 2007b) and Venus Express spacecraft (Häusler *et al.*, 2006). We made several modifications such as the redesign of the thermal insulating and mechanical shock protection system to adapt to the higher mechanical loads during the launch, resulting in dimensions (17 cm \times 13 cm \times 16 cm) and mass (1.9 kg) which are greater than for previous USOs. The USO is characterized by an excellent frequency stability; the Allan deviation is on the order of 10^{-13} at the integration time from 1 to 1000 s.

5.3 Signal processing

The phase fluctuation will be retrieved from the recorded signal in the following manner (Imamura *et al.*, 2005). In order to suppress the frequency variation to enable narrow-band filtering, a predicted Doppler frequency based on a model atmosphere is subtracted from the original signal by heterodyning. Then, approximate carrier frequencies are determined for successive time blocks by fitting theoretical signal spectra to the discrete Fourier transforms of the voltage variation in successive blocks (Lipa and Tyler, 1979). This frequency time series is divided into another set of successive blocks with time intervals of a few seconds, and smooth functions (such as spline) are determined to approximate the frequency variations in these blocks. Then the resultant frequency variation corresponding to the smooth functions is subtracted from the signal by heterodyning to apply another narrow-band filter.

The filtering scheme automatically converts the data to a complex representation, in which each datum comprises both the amplitude and phase of the signal. The low-noise signal generated by narrow-band filterings yields the phase by removing cycle slips via the phase unwrapping procedure (Mizuno *et al.*, 1992). The frequency is obtained by

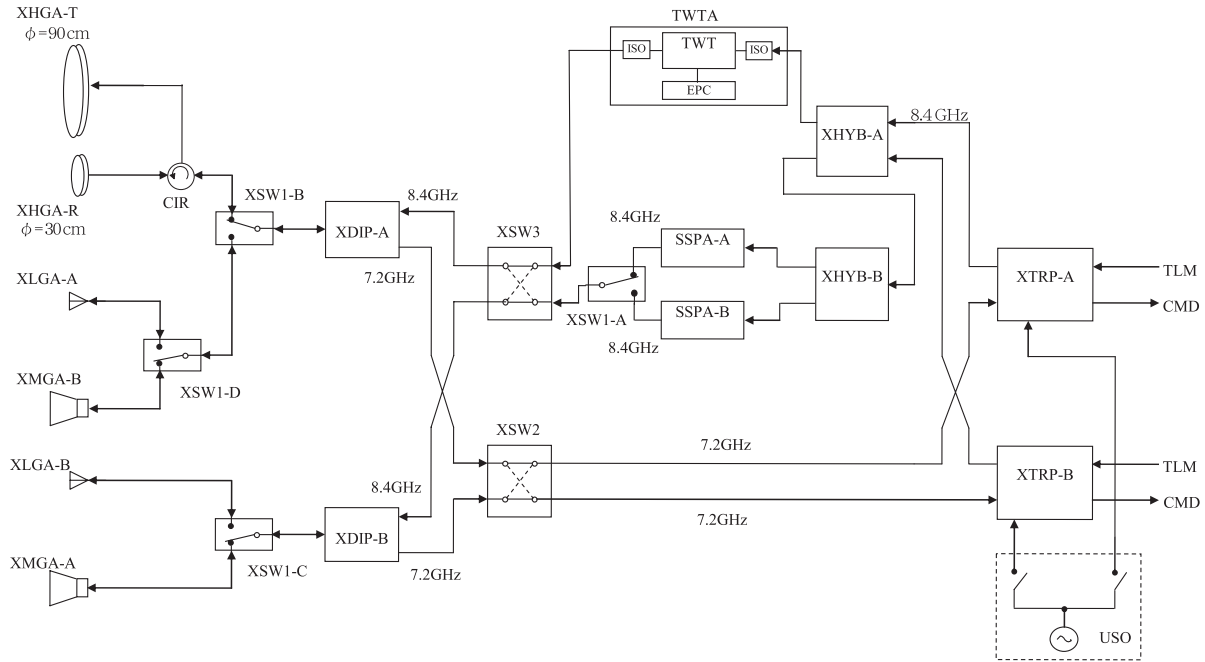


Fig. 5. Block Diagram of the Akatsuki communication subsystem (Courtesy of NEC TOSHIBA Space Systems, Ltd.).

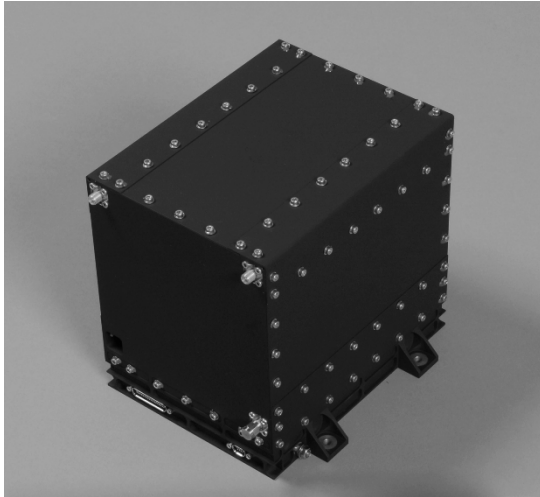


Fig. 6. Photograph of the USO onboard Akatsuki.

Table 1. Link budget of Akatsuki RS including losses for two Venus-Earth distances and for the minimum probed altitudes of 40, 60 and 80 km.

Distance (AU)	0.35	1.73
EIRP of transmission (dBW)	42.5	
Absorption and rain loss (dB)	−0.8	
Receiver pointing loss (dB)	−0.2	
G/T of ground station (dB/K)	52.7	
C/N_0 without Venus atmosphere (dBHz)	57.5	43.6
Defocusing loss for $D = 2 R_v$ (dB)		
40 km	−25.9	
60 km	−12.6	
80 km	−2.1	
Absorption loss (dB)		
40 km	−14.7	
60 km	−0.5	
80 km	0.0	
Overall C/N_0 (dBHz)		
40 km	16.9	3.0
60 km	44.4	30.5
80 km	55.4	41.5

differentiating the phase with respect to time. The sum of the frequency variation in this final product and the frequency variations that have been subtracted via heterodyning in the course of the processing gives the total atmospheric Doppler shift, from which the bending angle is calculated.

5.4 Link budget and error estimation

The distance between the Earth and Venus at occultation opportunities ranges from 0.35 AU (Astronomical unit) to 1.73 AU. Table 1 presents the link budgets including the defocusing and absorption losses, for the minimum and maximum Earth-Venus distances, and for the heights of the ray closest approach of 40, 60 and 80 km. The absorption loss is taken from Häusler *et al.* (2009).

The carrier-to-noise density ratio (C/N_0) of the received signal decreases significantly at low altitudes (40 km). This

low C/N_0 will be partially compensated by a long integration time, since at low altitudes the vertical movement of the ray path slows down due to the bending of the ray path. Moreover, the greater reflectivity of the lower atmosphere results in a higher sensitivity of the bending angle to the atmospheric temperature.

The statistical (random) uncertainty in the temperature should be on the order of 0.1 K or smaller for a prescribed vertical resolution of 1 km in the altitude region from 40 km to 80 km so that various atmospheric waves can be detected. To estimate the C/N_0 required for this purpose, we have computed the response of the downlink frequency to Gaussian-type temperature perturbations with a height of

0.1 K and a full-width of 1 km assuming an occultation geometry in which the ray transverse velocity relative to the Venus limb is its maximum, i.e. the case where the maximum time resolution is needed. The results showed that such temperature perturbations cause frequency perturbations roughly localized around the perturbed region. For altitudes around 80 km, a frequency resolution of ~ 0.03 Hz and a time resolution of ~ 0.1 s are needed to discriminate perturbations imposed on adjacent two layers separated by 1 km; this corresponds to a phase resolution of $\sigma \sim 0.019$ radians with a bandwidth of $B \sim 10$ Hz, giving a required C/N_0 of $B/2/\sigma^2 \sim 41.5$ dBHz. This value will be achieved according to the link budget analysis (Table 1). Similar analyses for 60 km and 40 km altitudes showed that the required C/N_0 is lower than the predicted C/N_0 for these altitudes. From these results we expect that the statistical error of the order of 0.1 K is possible. The influence of the fluctuation in the USO output frequency is negligible.

The systematic uncertainty in the temperature is difficult to estimate and is not presented in this paper. The sources of the error include the error in the spacecraft position, deviation from spherical symmetry of the atmosphere, long-timescale fluctuation of the transmit frequency, and possible multipath effect. An error estimation method given by Lipa and Tyler (1979) would be valid when the statistical characteristics of these errors are provided.

The accuracy of electron density measurement is limited at least by the fluctuation of the terrestrial ionosphere and is estimated to be on the order of 100 cm^{-3} based on the measurement of the ionospheric column density (Imamura *et al.*, 2010). The density fluctuation of the interplanetary plasma can also be an error source for small solar offset distances of the ray path. Based on the results of solar occultation measurements (Woo and Armstrong, 1979; Imamura *et al.*, 2005), the error is estimated to be $\sim 3000 \text{ cm}^{-3}$ for the solar offset distance of 0.1 AU, and decreases to $\sim 300 \text{ cm}^{-3}$ for 0.3 AU, given the typical time scale of traversing the Venus ionosphere of 10 s. It should be noted that these uncertainties vary with time.

6. Summary

A radio science investigation (RS) of the Venusian atmosphere will be conducted in the JAXA's Akatsuki mission. The observation targets of Akatsuki RS are (i) atmospheric temperature profiles for studying the thermal structure and atmospheric waves, (ii) sub-cloud H_2SO_4 vapor profiles for studying cloud physics, (iii) scintillation intensities for studying turbulence or gravity wave parameters, and (iv) ionospheric electron density profiles for studying ionosphere-solar wind interaction.

To achieve a high frequency stability in the X-band downlink signal, the spacecraft is equipped with an USO as a reference frequency source. During occultations the spacecraft will perform attitude maneuvers to compensate for the ray bending. The downlink signal will be recorded by an open loop receiver at the Usuda Deep Space Center of Japan. The frequency and intensity variations observed at the tracking station will be processed off-line, and the vertical structure of the Venus atmosphere will be derived assuming local spherical symmetry of the atmosphere.

The uniqueness of Akatsuki RS as compared to the previous radio occultation experiments at Venus is that low latitudes can be probed many times thanks to the near-equatorial orbit of the spacecraft. Systematic long-term sampling in the equatorial region provides a opportunity to observe the propagation of planetary-scale waves such as Kelvin waves and thermal tides, which might contribute to the maintenance of the super-rotation via eddy momentum transport. Covering the subsolar region is essential to the understanding of the cloud dynamics. Another advantage of Akatsuki RS is a suite of multiband cameras dedicated to meteorological study; the locations probed by RS will be observed by the cameras a short time before or after the occultations. The vertical profiles by RS and the horizontally-resolved information by the cameras complement each other in developing three-dimensional models of the atmosphere.

The Venus orbit insertion maneuver for Akatsuki on December 7, 2010 has failed. At present the spacecraft is orbiting the Sun, and it will have a chance to encounter Venus 5–6 years later. JAXA is examining the possibility of conducting an orbit insertion maneuver again at this opportunity.

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T. Imamura (e-mail: imamura.takeshi@jaxa.jp), T. Toda, A. Tomiki, D. Hirahara, T. Hayashiyama, N. Mochizuki, Z.-i. Yamamoto, T. Abe, T. Iwata, H. Noda, Y. Futaana, H. Ando, B. Häusler, M. Pätzold, and A. Nabatov